NORTHERN TERRITORY DEPARTMENT OF MINES & ENERGY

Operations and Processing Report

Airborne Geophysical Survey MARY RIVER Northern Territory

- September 2000

FLOWN AND PROCESSED BY KEVRON GEOPHYSICS FOR AND ON BEHALF OF THE NORTHERN TERRITORY DEPARTMENT OF MINES & ENERGY

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INTRODUCTION

The Mary River airborne geophysical survey lies on 1:250,000 maps Darwin (SD52- 04), Alligator River (SD52-01), Pine Creek (SD53-08), Mount Evelyn (SD53-05) and Katherine (SD53-09). A total of 47,555 line kilometres of magnetic, radiometric and digital elevation data were acquired and processed. It is intended that the acquired geophysical data will constitute a major addition to the fundamental geological database of the Northern Territory and will stimulate mineral exploration activity with a view to possible discovery and development of economic mineral deposits.

The project was managed by the Northern Territory Department of Mines & Energy, under the supervision of the Superintendent Mr. Richard Brecianini and Inspecting Officer, Mr. Roger Clifton. The data acquisition, quality control, data processing and mapping were carried out by Kevron Geophysics Pty Ltd of 10 Compass Road, Jandakot Airport, Western Australia.

Darwin and Katherine were used as the bases of operations for the duration of the Mary River survey. Mobilisation of crew commenced on $3rd$ July 2000 and all crew members were on site on $6th$ July 2000. Production commenced on $6th$ July and was completed on 18th August 2000. A total of 83 sorties were flown.

Acquisition was undertaken using a twin engine Aero Commander 'Shrike' 500s aircraft, registration VH KAV. Periodic maintenance was performed by Kevron Aviation staff at Aboriginal Aircraft Maintenance facilities in Alice Springs and on the ground at Darwin and Katherine.

The fixed wing traverse lines were flown at an interline spacing of 400 m, with a tie line spacing of 4000m. Traverse lines and tie lines were oriented 090° and 000E respectively. An average ground clearance of 80m was specified for both magnetic and radiometric sensors.

In field data verification and quality control was undertaken on a post flight basis onsite using a combination of Kevron proprietary software and ChrisDBF. QC products produced in the field included magnetometer $4th$ difference noise plots, flight path deviation plots of cross-track and elevation and radiometric summed spectra plots. Diurnal plots of the Cs vapour base station magnetometer were plotted and assessed to ensure contract compliance. Some reflights were necessary due to excessive magnetic variation. Back-ups of all field data were written to compact disk and an additional copy sent to Kevron's data processing center in Perth where further QC products were produced and data processing undertaken.

1. SURVEY AREAS AND PARAMETERS

1.1 SURVEY AREA

Total line kilometres for the MARY RIVER AREA was calculated to be 47,555 inclusive of tie lines and boundary overlap. A breakdown of the survey follows:

MARY RIVER NORTH (ZONE 52)

MARY R IVER SOUTH (ZONE 53)

The Mary River survey covers parts of the following 1:250 000 map sheets:

- Darwin SD52-4
- Alligator River SD53-1
- Pine Creek SD52-8
- Mt Evelyn SD53-5
- Katherine SD53-9

Mean daily maximum temperatures for Katherine (located on the Southern Boundary of the survey area) from July to September is 31 deg C.

Mean daily minimum temperatures for the same period is 14 deg C.

Mean daily maximum temperatures for Darwin (located on the North West of the survey area) from July to September is 33 deg C .

Mean daily minimum temperatures for the same period is 14 deg C .

The following geographic coordinates based on the GDA94 datum and spheroid define the survey boundary.

1. $12^{\circ}17^{\circ}S$, $131^{\circ}30^{\circ}E$, Then east along the coastline to 12°18'S, 132°05'E, then southwest along the boundary of Kakadu National Park to 12°31'S, 131°53'E, 12°55'S, 131°52'E, 12°55'S, 132°04'E, 13°10'S, 132°04'E, 13[°]10'S, 131°52'E, then south-east along the boundary of Kakadu National Park to 13°48'S, 132°22'E, 13°48'S, 132°41'E,

14°S, 132°41'E, 14oS, 133°E, 14°30'S, 133°E, 14°30'S, 132°E, 14°S, 132°E, 14°S, 131°30'E, 13°39'S, 131°30'E, 13°39'S, 131°39'E, 13°52'S, 131°56'E, 13°39'S, 131°47'E, 13°39'S, 132°E, 13°25'S, 131°58'E, 13°25'S, 131°49'E, 13[°]10'S, 131[°]40'E, 13°06'S, 131°40'E, 13°06'S, 131°38'E, 13°04'S, 131°38'E, 13°03'S, 131°32'E, 12°47'S, 131°31'E, 12°47'S, 131°15'E, 12°44'S, 131°15'E, 12°44'S, 131°13'E, 12°39'S, 131°13'E, and 12°39'S, 131°30'E.

Refer to *Appendix 1* for survey area location diagram.

1.2 SURVEY PARAMETERS

Time Base and approximate sampling interval (in still air):

- Magnetics 0.1 second (7 metres approx.)
-
-
- Radar altimeter 0.1 second (7 metres approx)
	- Radiometrics 1.0 second (70 metres approx.)
-
- GPS system 1.0 second (70 metres approx.)

2. LOGISTICS

2.1 OPERATIONS BASE AND SURVEY DATES

Darwin was selected as the initial operating base for the northern area. It provided all the facilities required for the safe operation of an airborne geophysical survey in a designated remote area. The southern half of the survey was carried out from Katherine.

Both Darwin and Katherine offer comfortable accommodation and eating establishments, important for crew morale on large projects. A regular service by Ansett subsidiary Air North allowed for the rapid dispatch of data to the DPC in Perth and the ability to rotate crews smoothly with little or no loss of production. Down time due to instrument failure was also minimised as replacement components could be despatched and delivered the following day.

Darwin airport has two bitumen runways: runway 11/29 being 3354 m in length and runway 18/36 being 1524 m in length. Navigation aids include VOR (DN 112.6), NDB (DN 334) and DME (DN 73X/112.6). AVGAS was readily available at reasonable cost from the Shell distributor..

Katherine / Tindal airport has a bitumen runway: runway 14/32 being 2744 m in length. Navigation aids include VOR (TDL 112.3), NDB (TDL 356). AVGAS was readily available at reasonable cost from the Shell / BP distributor.

Crew Accommodation:

DARWIN KATHERINE Stuart Highway Katherine Winnellie

Darwin Highway Inn Knotts Crossing Resort

2.1.1 Survey Dates and Production Summary

Refer to *APPENDIX 4* for detailed production summary.

2.2 SURVEY AIRCRAFT AND FIELD CREW

Aircraft Twin engine Rockwell Aero Commander 500S 'Shrike': Registration VH KAV

Field Crew Pilots **Pilots** Operators

P. Hillier D. Anderson T. Elefthariadis D. Little M. Rooney R. Deopel D. Chappell D. Gay R. Jamieson B. Gribble M.Cote

Crew Leader & Field QC D. Gay / B.Gribble

3. SURVEY EQUIPMENT, OPERATION AND QUALITY CONTROL

3.1 MAJOR EQUIPMENT SUMMARY

3.2 MAGNETOMETER AND COMPENSATOR

A Geometrics G-822A optically pumped caesium vapour magnetometer was used for the survey with the sensor mounted in a tail stinger on each aircraft. The magnetometer sensor was coupled to a RMS Instruments Automatic Aeromagnetic Digital Compensator (AADC) to produce real time compensation for the effects of the aircraft's motion, changes in attitude and heading. The AADC interference coefficients were calculated from compensation flights carried out before the survey commenced and after aircraft maintenance. The AADC output data, with a resolution and sensitivity of 0.001 nT at a sampling rate of ten (10) times per second, were recorded digitally and in analogue form. The noise envelope for compensated magnetometer readings was less than 0.1 nT

3.2 BASE STATION MAGNETOMETER

A caesium vapour base station magnetometer was used to measure the daily variations of the Earth's magnetic field. The base station was established in an area of low gradient, away from cultural influences. These data were displayed and recorded on a Libretto laptop computer. The base station was run continuously throughout the survey flying period with a sampling interval of 1 seconds and a sensitivity of 0.01 nT.

In addition to the caesium vapour base station, a Geometrics G856 proton precession magnetometer base station recording at 5 second intervals was established at the base airstrip, primarily as a storm monitor.

The base station data were closely examined after each days production flying to determine if any data had been acquired during periods of out-of-specification diurnal variation.

3.3 SPECTROMETER

A Geometrics GR-820D double buffered, 256-channel gamma ray spectrometer with automatic crystal gain and temperature control was used to record 256 channels of data in addition to the data from five pre-set spectral windows. Total downward crystal array volume was 33.6 litres. System sample time and live time were also recorded. The digital data and four channels of analogue data were recorded once per second.

The pre-set spectral window limits were:

The analogue data were corrected for dead time, normalised and stripped for Compton scattering.

3.4 ALTIMETERS

A Sperry AA-210 Radio Altimeter system was used to measure ground clearance. The radio altimeter indicator provides an absolute altitude display from 0 - 750 metres $(0 - 2,500$ feet) with a sensitivity of 4 mV/ft.

A Rosemount 1241m barometer, with an output sensitivity of 0.666 mV/ft, was used to measure atmospheric pressure and barometric altitude of the aircraft.

Data from both altimeters were recorded on digital tape and on the analogue chart.

The radar altimeter system was checked prior to commencement of production flying. This involved flying the aircraft at 30 metre height intervals, up to a height of 300 metres over the base of operations airstrip using the aircraft's barometric altimeter as the height reference. Radar altimeter and GPS height data were recorded for each flight interval flown. A comparison of these data with the aircraft's barometric altimeter verified that the system was operating satisfactorily.

Altimeter data (radar and barometric) were digitally recorded every 0.1 seconds.

3.5 NAVIGATION AND FLIGHT PATH RECOVERY

Aircraft navigation was controlled by real-time differential GPS using an Ashtech XII "Ranger" receiver in the aircraft with pseudo range corrections obtained through the commercial FUGRO system transmitting via the OPTUS B satellite. The horizontal position of the aircraft was fixed and recorded once per second. The

on-board pilot guidance steering signal was updated once every half second.

The pseudo range information was recorded every 5 seconds at both the aircraft receiver and also at a base station receiver located at the Hotel accommodation at both Bases of Operation (*APPENDIX 2*). The raw GPS data were differentially corrected post flight to give corrected GPS positional data accurate to 5 metres or less RMS.

The position of the base station GPS receiver was accurately determined by differential GPS surveying using the $2nd$ order trigonometrical station.:

The determined base station GPS coordinates (WGS 84) were:

The post-processed flight path data were inspected after each flight for any deviations of flight path from specifications and for any gaps caused by momentary loss of satellites. Flight path quality was confirmed at Kevron's processing centre by maps, plotted from the real time data recorded on magnetic tape, highlighting any portions of lines which exceeded the specified horizontal and altitude tolerances.

3.6 FLIGHT TRACK RECORDING SYSTEM

The flight path of the aircraft was recorded with a National CCD colour video camera and a VHS video recorder. Line and fiducial numbers were recorded on the video image.

3.7 DATA ACQUISITION

A RMS Instruments DAS-8 Data Acquisition System was used to record all data in digital format onto a PC 6 gigabyte hard disk drive. Analogue information was recorded on a RMS Instruments GR-33A printer-plotter.

In general, the following parameters were recorded at the scales indicated; however, each analogue chart was stamped with the parameters and scales recorded:

The analogue chart recorder and various digital displays were used by the Operator to monitor data quality during a flight.

3.8 GENERAL QUALITY CONTROL

Rigorous in-field quality control was undertaken on-site and various QC products were produced in the field using a combination of Kevron proprietary software, ChrisDBF software and AGSO software. QC plots were produced for each flight and included:

- Flight path maps displaying cross track and height deviations.
- \blacksquare Magnetic 4th difference noise plots
- Radiometric Summed spectra plots
- Diurnal plots

Lines selected at random from each flight were subjected to further QC checks. Profiles were generated for all variables recorded and inspected for data quality. Any lines found to be outside the specified tolerances were identified and reflown.

A running log of each flight was maintained recording details of all lines flown. Transcribed flight logs are included in *APPENDIX 3*. Equipment tests and calibrations are described in Section 4 and tabulations of the calibration and test flight data are in *APPENDIX 6.*

Field data were sent to Kevron's processing centre in Perth where they were further inspected for data quality and conformance to specifications before commencing processing.

3.10 SAFETY MANAGEMENT

All aircraft operations, including pilot flying hours and aircraft maintenance, complied with the requirements of the Federal Civil Aviation Safety Authority (CASA) and the CASA-approved procedures set out in Kevron's Aircraft Operations Manual.

The ground support vehicle was equipped with adequate radio equipment to enable two-way communication with the aircraft and/or the RFDS. Search and Rescue times for vehicles in remote areas are a Company requirement.

4. CALIBRATIONS

4.1 MAGNETICS

Compensation coefficients for the AADC were established by flying a "compensation box" test (a series of pitch, roll and yaw manoeuvres in each of the four cardinal headings) before survey production commenced, and again after aircraft servicing where components were changed that may effect the magnetic field of the aircraft.

Compensation flights were flown in an area of low gradient approx. 35 nm SW of Tennant Creek at an altitude of 8000 to 10000 feet above mean sea level.

The AADC calculates basic statistics, which reflect the degree of merit of the compensation. These include the standard deviation of the recorded data without corrections applied, the standard deviation with the correction applied, the improvement ratio (the ratio of the standard deviation of the recorded data without and with corrections applied) and the vector norm (the degree of difficulty in calculating the corrections. The table below shows statistics recorded from compensation flights with the aircraft in survey configuration, ie Air conditioner on, Transponder off, DME off, HF on, ADF on, #1 COM on, #2 NAV/Com on .

4.2 RADIOMETRICS

4.2.1.Background Correction Plots and Equations

The following procedure was used to determine the aircraft background radiation. There were no changes to the system between the date of this test and the survey.

- a) A stack of nine lines were flown over water, west of the Perth coast, at altitudes from 1 000 ft to 9 000 ft. with increments of 1 000 feet.
- b) The counts in the Potassium, Uranium, Thorium, Total Count and Cosmic channels were corrected for dead time and scaled to counts per second for all lines.

The measured 256 channel spectra are each the sum of the aircraft component (constant) and the cosmic component. The measured spectra are used to calculate the aircraft gamma energy spectrum and the normalised cosmic gamma energy spectrum.

Aircraft and Cosmic background spectra are estimated as follows:

$$
N_i = a_i + b_i N_{cos}
$$

Where:

$$
N_i = \text{ aircraft} + \text{cosmic background count rate in the } (i) \text{th channel}
$$

 N_{cos} = cosmic window count rate

$$
a_i
$$
 = aircraft background in the (*i*)th channel

i **= cosmic background in the (***i***)th channel normalised top unit** counts in the cosmic window.

A linear regression of the cosmic window count rate on any channel gives the cosmic sensitivity (slope of regression line) and aircraft background (zero intercept) for that channel.

The aircraft and cosmic background spectra are subtracted from the dead-time corrected and energy calibrated observed spectra, The conventional radiometric windows are extracted from the 256 channel data.

4.2.2 Pre and Post Flight Checks

Hand sample checks, using thorium, uranium and caesium-137 samples, were carried out before and after flights. A statistical summary of the checks is presented in *APPENDIX 6*.

4.2.3 Test Line

A test line approximately 8 kilometres long was chosen at each Base of Operations. The start and end co-ordinates are as follows;

4.2.4 Compton Stripping Coefficients

The following Compton stripping coefficients, derived from calibrations over test pads in Perth were used to correct the count rates displayed on the analogue chart and in subsequent processing:

4.2.5 Spectrometer Countrate Sensitivities

Broad source sensitivities for each of the radio-element windows were obtained from a flight line flown at a height of 60 m over the Carnamah Test Range and a corresponding line on the ground surveyed with a calibrated hand-held spectrometer supplied by Tesla Geoscience. The Carnamah Test Range is located approximately 10 kilometres east of Carnamah, 200 kilometres north of Perth, on the Carnamah-Belvoir Road. The Test Range follows the power line south for eight kilometres crossing undulating wheat crops and rocky scrub covered hills.

The aircraft acquisition system was not changed between the date of the calibration flight and the survey dates. The following values were obtained:

VH KAV 2^{nd} July, 2000

4.3 PARALLAX

The parallax error was established immediately after completion of the survey by flying over a suitable anomaly in opposite directions. The parallax for each aircraft system was resolved to following:

Magnetics 5 fiducials (all flights) **Radiometrics** No parallax correction was applied to the radiometrics

5. DATA PROCESSING

5.1 DATA VERIFICATION AND EDITING

The field data were sent regularly to Kevron's processing centre in Perth for verification and editing with in-house software installed on Sun Sparc 20 workstations.

The data were loaded into a database and a statistical report generated for each variable on a line by line basis. The data were then edited for scrubbed or duplicate lines and checked for spikes, steps or high noise levels. Lines with any out-ofspecification data were flagged for reflight.

5.2 FLIGHT PATH RECOVERY

The differentially corrected GPS data were converted to Universal Transverse Mercator coordinates using the Australian National Spheroid.

The survey area is in grid UTM Zone 52 with a central meridian of 132° East.

Flight path maps were generated to verify the off-line tolerances and to make sure all necessary data had been loaded into the geophysical data base.

5.3 MAGNETIC PROCESSING

After correcting the magnetic data for diurnal variations, the International Geomagnetic Reference Field (IGRF) was subtracted and the data were tie line levelled.

These processes are described more fully below.

5.3.1 Diurnal Correction

The diurnal data were edited to keep only those readings taken during flight time. The data were visually checked on the computer screen for spikes, noise and any apparent cultural magnetic events.

After editing, the data were low pass filtered using a twenty-term, spatial domain filter, which removed periods of less than thirty seconds. The data were again checked visually for integrity after the filtering process.

The filtered data were synchronised with the airborne data, interpolated and subtracted from the airborne data, one sample at a time. After subtraction, the mean diurnal value was added back to the airborne data for each line to produce diurnally corrected data.

5.3.2 Subtraction of the IGRF

The International Geomagnetic Reference Field (IGRF) was removed from the diurnally-corrected data by fitting a second order polynomial surface to thirteen coefficients computed from the IGRF model and then subtracting the IGRF values on a sample by sample basis.

The IGRF 1995 model updated to the survey date was used with the following

values:

5.3.3 Tie Line Levelling

The diurnally corrected and IGRF-removed data were processed by a Kevron proprietary levelling program.

The program compares the magnetic differences at intersections of the flight lines and tie lines and calculates individual magnetic field biases for each flight line based on the tie line intersection. The miss-ties are minimised in a least-squares sense for all intersections. The biases are manually evaluated and selectively applied. Further reduction of the miss-ties can be removed by fitting a polynomial to produce levelled magnetic data.

The levelled data were then gridded on a 100 x 100 metre mesh using a minimum curvature algorithm based on Briggs (1974). The gridded data were displayed on an image processor to check data integrity and data levelling.

5.3.4 Micro Levelling

The data were microlevelled using Kevron in-house proprietary software. Kevron's micro-levelling process is line based rather than grid based. Pseudo lines are extracted perpendicular to the traverse line direction. These are low pass filtered and mis-tied to the traverse lines using the tie line levelling software.

The mis-tie values are bounded spatially by a series of polygons edited through ER Mapper.

5.4 RADIOMETRIC PROCESSING

5.4.1 System Deadtime and Energy Calibrations

Following correction for system deadtime, the 256 channel spectrometer data were energy calibrated using the following procedure:

For each line, the individual 256 channel data from each sample point were stacked to produce a single spectrum. The peak positions of the standard potassium and thorium windows were found by performing a gaussian fit to the spectral data for the energy range of each window after first removing the Compton continuum slope. If the measured peak positions were shifted by more than one channels for the thorium peak or 0.5 channels for the potassium peak, an energy recalibration was performed to obtain the correct spectral channel positions for the lower and upper bounds of each of the required windows. Using these corrected channel limits, new window counts were then extracted from the 256 channel data for each

1 second data sample on the line.

5.4.2 Maximum Noise Fraction (MNF)

Statistical noise reduction of the 256 channel data was performed using the Maximum Noise Fraction (MNF) method described by Dickson and Taylor (1998). This method constructs a noise covariance model from the survey data, which is then decorrelated and re-scaled so that the model has unit variance and no channelto-channel correlation.

A principal component transformation of the noise-whitened data is performed, and the number of components to be saved is determined by ranking the eigenvectors by signal-to-noise ratio. The signal-rich components are retained, and the spectral data reconstructed without the noise fraction. Typically, 32-42 MNF components are retained during this process. Channels 30-250 only are noisecomponents are retained during this process. cleaned, as these contain the regions of interest and are not dominated by the lower end of the Compton continuum.

Data has been tie-levelled and micro-levelled to remove minor residual errors.

5.4.3 Aircraft and Cosmic Background Removal

Aircraft and cosmic background were removed from the data using the normalised 256 channel cosmic spectrum for the aircraft, and the aircraft 256 channel background spectrum. Cosmic & Aircraft background removal

5.4.4 Airborne radon removal

Data were corrected for airborne radon using Minty (1996 – Alt Method B) two component spectral ratio method

Calibration constants for Method B derived directly from observed radon and ground spectra at a height of 60m STP. C_L and $C₂$ are the ratios between the 0.609 MeV peak count rate and the conventional U window count rate for a radon spectrum and a composite K, U and Th ground spectrum respectively.

5.4.5 Effective Altitude Calculations and Compton Scattering Corrections

At this point, the conventional radiometric windows are extracted from the 256 channel data and all further gamma-ray corrections are performed using threewindow radiometric data processing.

Following reduction of the altitude data to effective altitude at standard temperature and pressure as described in Grasty and Minty (1995), Compton scattering stripping was carried out on the background corrected count rates in the potassium, uranium and thorium channel data using the coefficients listed in Section 4.2.4.

5.4.6 Height attenuation corrections

A height attenuation factor was applied to reduce the data for each channel to a nominal datum of 80 m above ground level. The program used limits corrections to

data at terrain clearances between 30m and 250m. Data recorded at terrain clearances outside these limits are corrected assuming they are at these limits.

The attenuation factors used are listed below and were determined from tests carried out over the Carnamah Test Range.

5.4.7 Conversion -Ground Element Concentrations

Data were converted to equivalent ground concentrations using the method described in Grasty and Minty (1995) using, for each window, the equation:

$$
C_i = N_i / S_i
$$

where $C_i =$ ground concentration of radio-element "i" (%K, ppm eU or ppm eTh);

 N_i = corrected count rate for window "i"; and

 S_i = broad source sensitivity for window "i" as tabled in Section 4.2.5.

5.4.8 Levelling

The corrected and reduced radiometric data were tie-line levelled and mircolevelled using the procedure described above for the magnetic data.

5.5 DIGITAL ELEVATION MODEL

A digital elevation model (DEM) was computed by subtracting the terrain clearance measured by the radar altimeter from the GPS measured aircraft altitude to obtain a nominal ground elevation. The nominal ground elevation data were tie-line levelled and micro-levelled using the same technique described for the levelling of the magnetic data.

Allowance was made for the constant 3.9 m elevation difference between the radar altimeter and the GPS antenna.

A set of geoid-ellipsoid separation values were obtained from AUSLIG, gridded and values interpolated for each point along the survey lines. The interpolated separation values were subtracted from the nominal ground elevation to produce the final located DEM.

The DEM data were tie line levelled and micro-levelled using the procedure described above for the magnetic and radiometric data.

5.6 DELIVERABLE ITEMS

The following survey data items were produced and delivered:

5.7 FINAL PRODUCTS

The following map products were produced at a scale of 1:250,000 for the entire area. All maps were produced using a combination of Kevron's proprietary software and ER Mapper.

Preliminary maps, images and grids were produced for assessment of data quality.

- (a) Hardcopy located images at 1:250 000 scale of;
	- (i) colour gradient enhanced total magnetic intensity and,
	- (ii) colour gradient enhanced total magnetic intensity RTP
		- (iii) greyscale first vertical derivative of RTP TMI and,
		- (iv) colour gradient enhanced total-count and,
		- (v) colour gradient enhanced potassium and,
		- (vi) colour gradient enhanced uranium and,
		- (vii) colour gradient enhanced thorium and,
		- (viii) ternary gamma-ray spectrometrics and,
		- (ix) colour gradient enhanced digital elevation model.
- (c) DGN files were supplied for the following;
	- (i) Flight Path
	- (ii) Total magnetic intensity colour contours,
	- (iii) Total-count colour contours,
	- (iv) Potassium colour contours,
	- (v) Uranium colour contours
	- (vi) Thorium colour contours

- (vii) Magnetic Stacked Profiles
- (d) Mosaic hard copy maps were supplied at a scale of 1:250,000 for the following:
	- (i) Flight Path
	- (ii) TMI colour contours
	- (iii) TC colour contours
	- (iv) Potassium colour contours
	- (v) Uranium colour contours
	- (vi) Thorium colour contours
	- (vii) Magetic stacked profiles

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Hovgaard, J. and Grasty, R.L, (1997). Reducing noise in airborne gamma-ray data through spectral component analysis. Exploration 97, Ontario Geological Survey.

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APPENDIX 1 – SURVEY AREAS AND FLIGHT PATH PLOTS

APPENDIX 2 – GPS BASE STATION LOCATION

APPENDIX 3 – OPERATORS FLIGHT REPORTS

APPENDIX 4 – WEEKLY PRODUCTION SUMMARIES

APPENDIX 5 – BASE STATION MAGNETOMETER PLOTS

APPENDIX 6 – RADIOMETRIC CALIBRATIONS

APPENDIX 7 – RADIOMETRIC BACKGROUND PLOTS

APPENDIX 8 – LOCATED DATA TAPE FORMATS

DEFN ST=RECD,RT=COMM;RT:A4;COMMENTS:A76 DEFN 1 ST=RECD,RT=;LINE:A8:NULL=-999999,NAME=Line number DEFN 2 ST=RECD,RT=;FLIGHT:I4:NULL=-99,NAME=Flight number DEFN 3 ST=RECD,RT=;DATE:A9:NULL=-9999999,NAME=Date (YYYYMMDD) DEFN 4 ST=RECD,RT=;TIME:F9.5:NULL=-9.99999,UNIT=hours,NAME=Time (CST) DEFN 5 ST=RECD,RT=;FIDUCIAL:F10.0:NULL=-9999999.,NAME=Fiducial DEFN 6 ST=RECD,RT=;LATITUDE:F11.6:NULL=-99.999999,UNIT=dega,NAME=Latitude DEFN 7 ST=RECD,RT=;LONGITUD:F11.6:NULL=-99.999999,UNIT=dega,NAME=Longitude DEFN 8 ST=RECD,RT=;ZONE:I3:NULL=-9,NAME=Zone DEFN 9 ST=RECD,RT=;EAST:F11.2:NULL=-999999.99,UNIT=metres,NAME=MGA Easting DEFN 10 ST=RECD,RT=;NORTH:F11.2:NULL=-999999.99,UNIT=metres,NAME=MGA Northing DEFN 11 ST=RECD,RT=;RAW_TC:F7.0:NULL=-9999.,UNIT=cps,NAME=Raw total count DEFN 12 ST=RECD,RT=;RAW_K:F5.0:NULL=-99.,UNIT=cps,NAME=Raw potassium DEFN 13 ST=RECD,RT=;RAW_U:F5.0:NULL=-99.,UNIT=cps,NAME=Raw uranium DEFN 14 ST=RECD,RT=;RAW_TH:F5.0:NULL=-99.,UNIT=cps,NAME=Raw thorium DEFN 15 ST=RECD,RT=;COSMIC:F5.0:NULL=-99.,UNIT=cps,NAME=Cosmic DEFN 16 ST=RECD,RT=;TC:F9.2:NULL=-9999.99,UNIT=nGy/h,NAME=Total count DEFN 17 ST=RECD,RT=;K:F9.2:NULL=-9999.99,UNIT=%,NAME=Potassium DEFN 18 ST=RECD,RT=;U:F9.2:NULL=-9999.99,UNIT=ppm,NAME=Uranium DEFN 19 ST=RECD,RT=;TH:F9.2:NULL=-9999.99,UNIT=ppm,NAME=Thorium DEFN 20 ST=RECD,RT=;LIVETIME:F6.0:NULL=-999.,UNIT=ms,NAME=Live time DEFN 21 ST=RECD,RT=;PRESS:F7.1:NULL=-999.9,UNIT=hPa,NAME=Pressure DEFN 22 ST=RECD,RT=;TEMP:F5.1:NULL=-9.9,UNIT=degrees C,NAME=Temperature DEFN 23 ST=RECD,RT=;HUMID:F5.1:NULL=-9.9,UNIT=%,NAME=Humidity DEFN 24 ST=RECD,RT=;RADALT:F7.1:NULL=-999.9,UNIT=metres,NAME=Radar altitude DEFN 25 ST=RECD,RT=;BAROALT:F7.1:NULL=-999.9,UNIT=metres,NAME=Barometric altitude DEFN 26 ST=RECD,RT=;GPSALT:F7.1:NULL=-999.9,UNIT=metres,NAME=GPS altitude;END DEFN

COMM LOCATED DATA FORMAT: \overline{C}

Kevro *Geophysics Pty Ltd* *Flown and Processed for Northern Territory Department Of Mines &Energy*

Flown and Processed for Northern Territory Department Of Mines &Energy

Kevron Flown and Processed for Northern Territory Department Of Mines &Energy

Flown and Processed for Northern Territory Department Of Mines &Energy

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APPENDIX 9 – EQUIPMENT TECHNICAL SPECIFICATIONS

SURVEY EQUIPMENT:

Aircraft: Rockwell Aerocommander 500S VH-KAV
Magnetometer: G-822A Cesium Vapour Geometrics G-822A Cesium Vapour
0.001 Magnetometer Resolution (nT):
Magnetometer Compensation: RMS AADCII operating in real time 0.1 Magnetometer Sample Rate (s): Magnetometer Sample Interval (m): approx 7.0 metres Base Station Magnetometer: G856
Base Station Magnetometer Resolution (nT): 1
1 Base Station Magnetometer Resolution (nT): Base Station Magnetometer Sample Rate (s): 5
Base Station Magnetometer Location(s): Darwin Airport Base Station Magnetometer Location(s): Spectrometer: Exploranium GR-820
Crystal volume: 32 litres Crystal volume: 32 l
Spectrometer Sample Rate (s): 1.0 Spectrometer Sample Rate (s): 1.0
Spectrometer Sample Interval (m): 2013 approx 70.0 metres Spectrometer Sample Interval (m): Data Acquisition System: RMS DAS8 Flight Path Navigation System: GPS
Navigation Equipment: Fugr Fugro Omnistar and Ashtech G12 GPS Radar Altimeter: Sperry AA200

APPENDIX 10 – HEIGHT DIFFERENCE CROSS-OVERS

Supplied digitally as floppy – xover_north & xover_south

